

# Elementarni vremenski kontinualni signali

- prostoperiodični signal

$$x(t) = A \cos(2\pi f_0 t + \theta) = A \cos\left(\frac{2\pi}{T_0} t + \theta\right) = A \cos(\omega_0 t + \theta)$$

- Kompleksni eksponencijalni signal

$$x(t) = A e^{(\sigma_0 + j\omega_0)t} = A e^{\sigma_0 t} [\cos(\omega_0 t) + j \sin(\omega_0 t)]$$

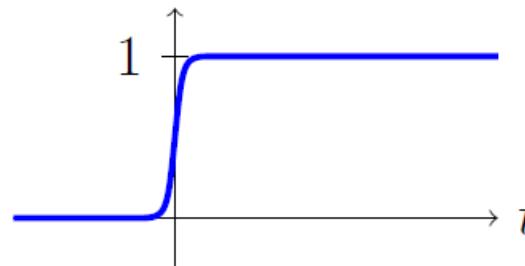
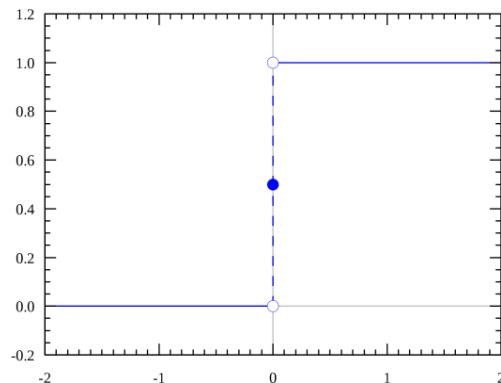
- signum funkcija

$$\operatorname{sgn}(t) = \begin{cases} 1 & t > 0 \\ 0 & t = 0 \\ -1 & t < 0 \end{cases}$$

# Elementarni vremenski kontinualni signali

- Hevisajdova odskočna ( $\theta$ ) funkcija
- half-maximum convention
- (Jedinična odskočna funkcija)

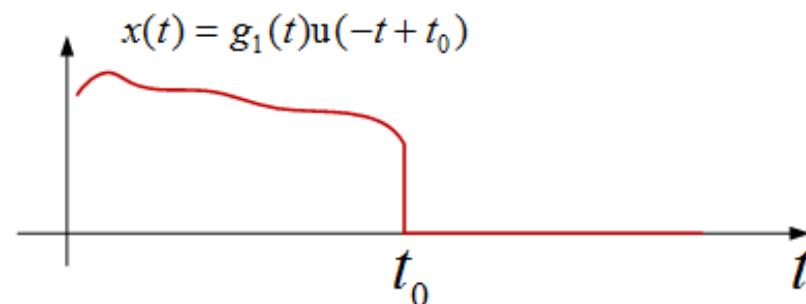
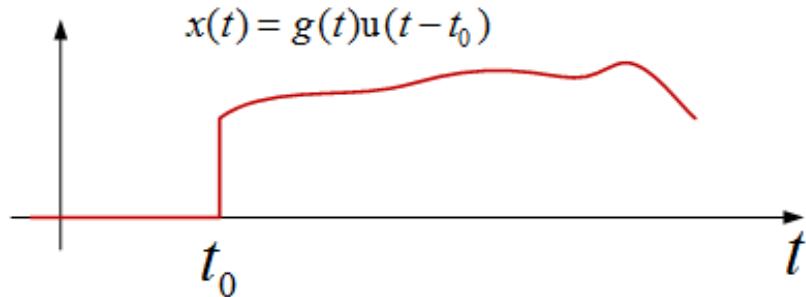
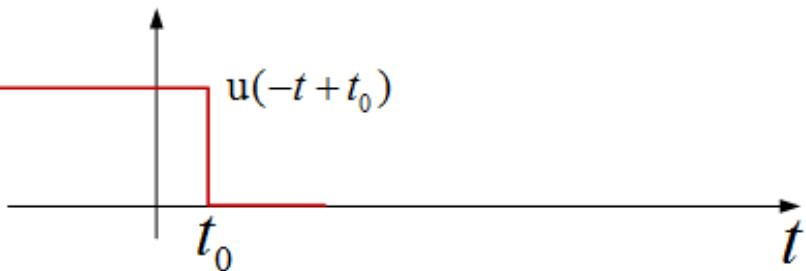
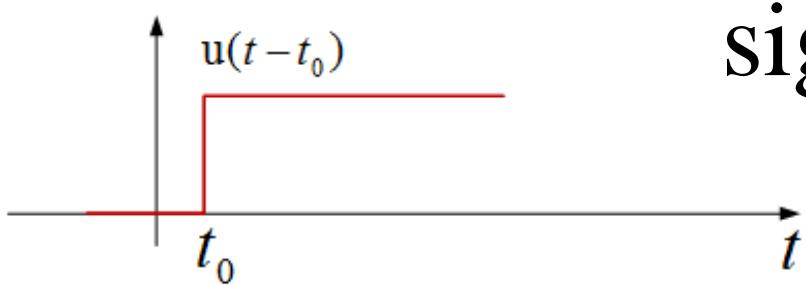
$$u(t) = \begin{cases} 1 & t > 0 \\ 1/2 & t = 0 \\ 0 & t < 0 \end{cases}$$



Modelovan “realan signal”

- Veza sa Signum funkcijom  $u(t) = \frac{1 + \text{sgn}(t)}{2}$
- U literaturi se mogu naći alternativne **definicije jedinične odskočne funkcije** gde je vrednost  $u(0)$  jednaka 0, 1, ili se ostavlja nedefinisano

# Elementarni vremenski kontinualni signali



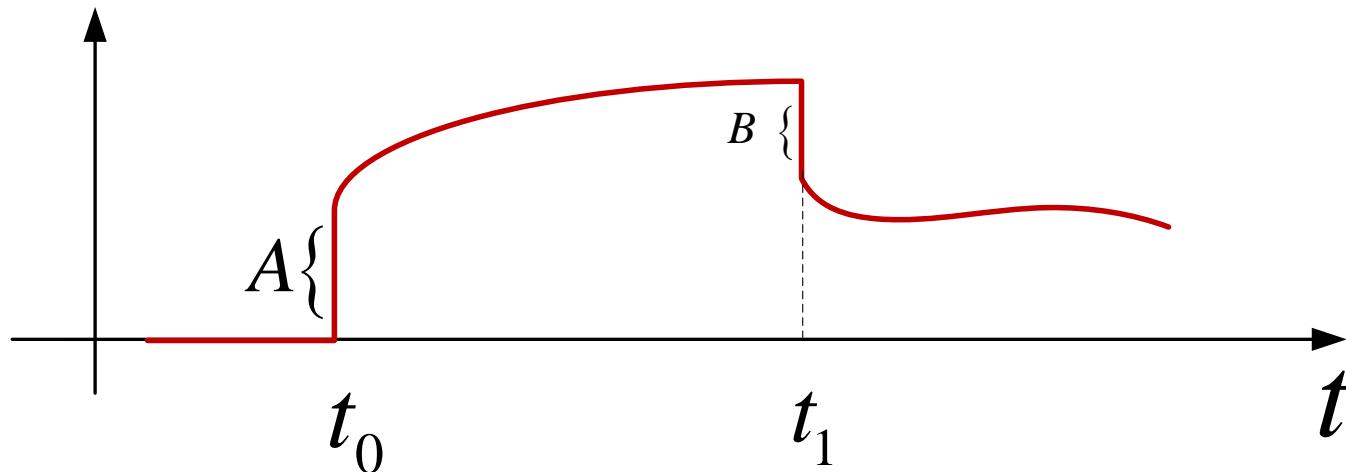
- Konstrukcija deo po deo glatke krive pomoću  $u(t)$

# Elementarni vremenski kontinualni signali

- Konstrukcija deo po deo glatke krive pomoću  $u(t)$

$$t_1 > t_0 > 0$$

$$x(t) = g(t)(u(t - t_0) - u(t - t_1)) + g_1(t)u(t - t_1)$$



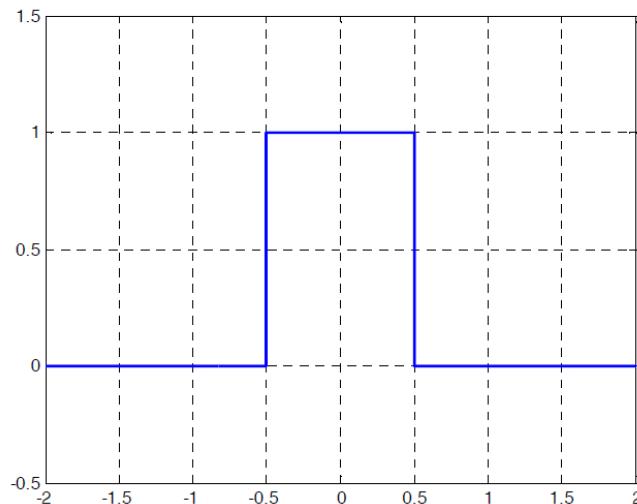
# Elementarni vremenski kontinualni signali

- Pravougaoni jedinični impuls

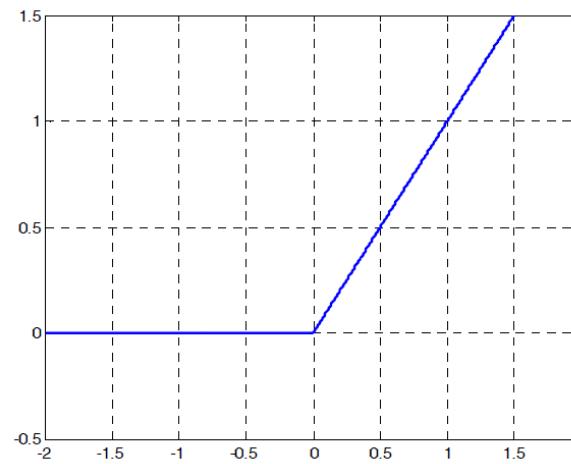
$$\text{rect}(t) = \begin{cases} 1 & |t| < 1/2 \\ 1/2 & |t| = 1/2 \\ 0 & |t| > 1/2 \end{cases}$$

- jedinična linearna funkcija

$$\text{ramp}(t) = \begin{cases} t & t > 0 \\ 0 & t \leq 0 \end{cases}$$



Površina 1



$$\text{ramp}(t) = t \cdot u(t) = \int_{-\infty}^t u(\tau) d\tau$$

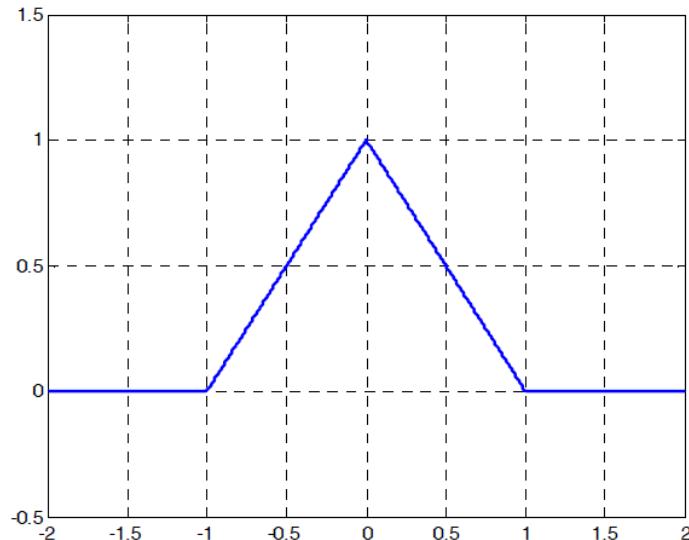
# Elementarni vremenski kontinualni signali

- Jedinična trougaona funkcija

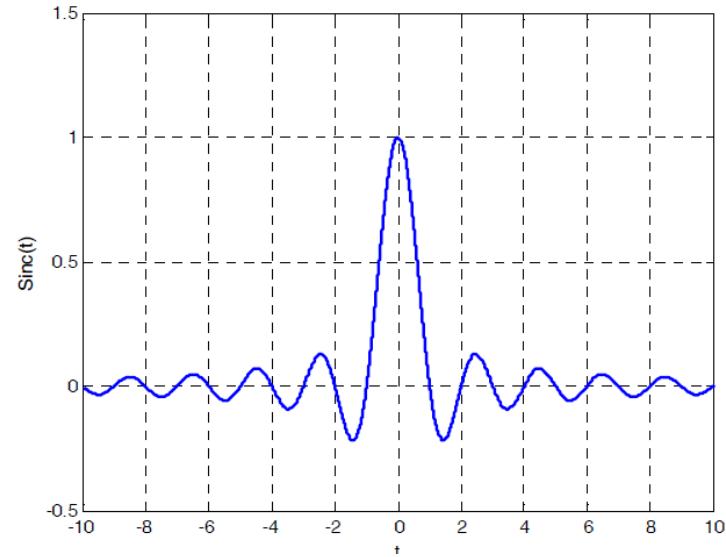
$$\text{tri}(t) = (1 - |t|) \cdot (u(t+1) - u(t-1))$$

$$\text{tri}(t) = \begin{cases} 1 - |t| & |t| < 1 \\ 0 & |t| \geq 1 \end{cases}$$

- Jedinična Sinc funkcija:  $\text{Sinc}(t) = \frac{\sin(\pi t)}{\pi t}$     $\text{Sinc}(n) = \frac{\sin(\pi n)}{\pi n} = 0$     $\text{Sinc}(0) = 1$

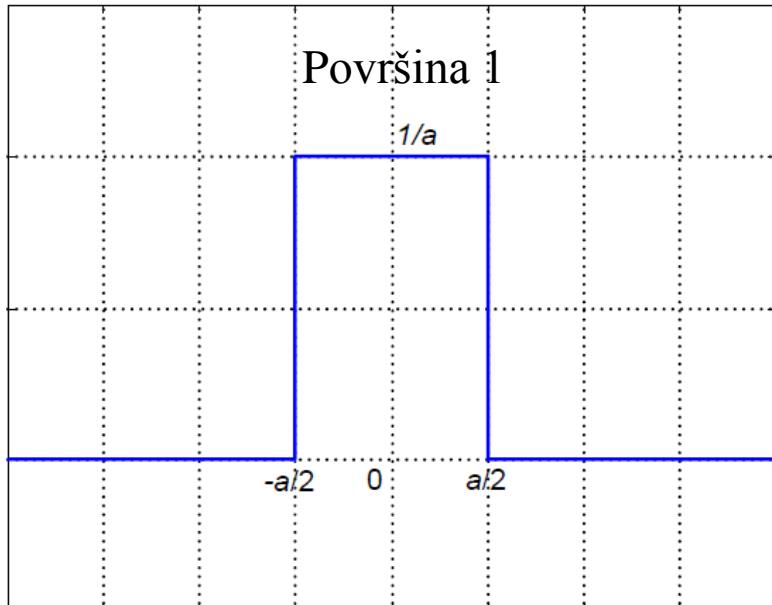


Površina 1

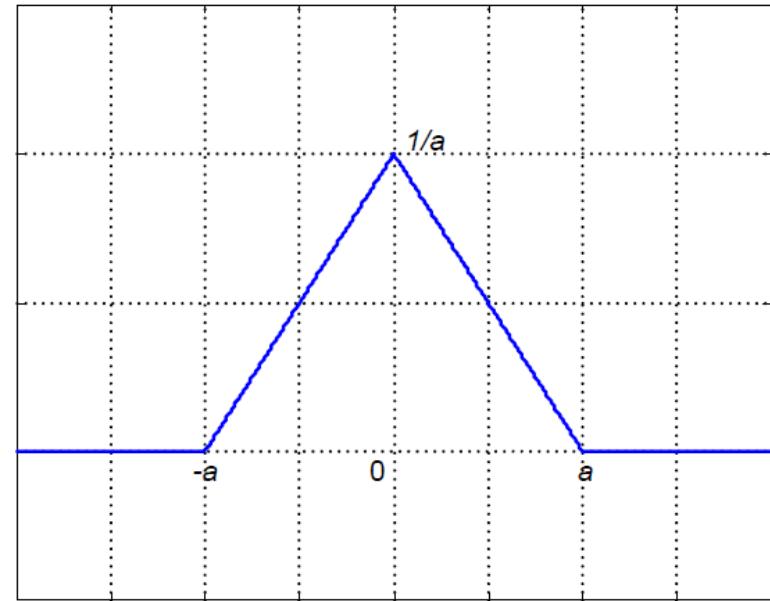


# Elementarni vremenski kontinualni signali koji se ne opisuju klasičnim funkcijama

- Jedinični impuls (Dirakov delta impuls)
- Granični proces



$$\delta_a(t) = \begin{cases} 1/a & |t| < a/2 \\ 0 & |t| > a/2 \end{cases}$$



$$\delta(t) = \lim_{a \rightarrow 0} \delta_a(t)$$

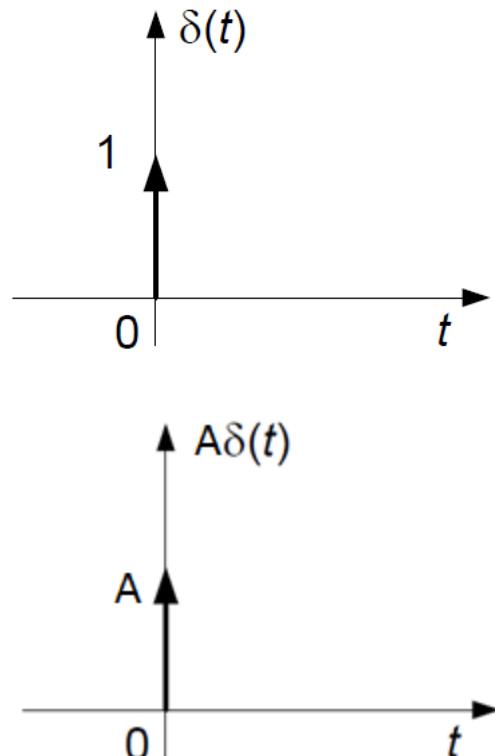
# Delta impuls

$$\delta(t) = 0, \text{ za } t \neq 0$$

$$\int_{-\infty}^{+\infty} \delta(t) dt = 1$$

$$\int_{t_1}^{t_2} \delta(t) dt = \begin{cases} 1 & \text{za } t_1 < 0 < t_2 \\ 0 & \text{drugde} \end{cases}$$

$$\int_{t_1}^{t_2} A\delta(t) dt = A \int_{t_1}^{t_2} \delta(t) dt \begin{cases} A & \text{za } t_1 < 0 < t_2 \\ 0 & \text{drugde} \end{cases}$$



- Delta impuls ima “beskonačnu amplitudu”,
- koristi se simbolička predstava pomoću vertikalne strelice,
- Visina strelice predstavlja “površinu” ispod signala
- označava se pisanjem odgovarajuće konstante  $A$  *pored impulsa na grafiku*.

# Svojstvo odabiranja (odmeravanja) Dirakovog impulsa

- Ako je  $x(t)$  neprekidna u okolini 0

$$\int_{-\infty}^{\infty} x(t)\delta(t)dt = \lim_{a \rightarrow 0} \int_{-\infty}^{\infty} x(t)\delta_a(t)dt = \lim_{a \rightarrow 0} \frac{1}{a} \int_{-a/2}^{a/2} x(t)dt = x(0) \lim_{a \rightarrow 0} \frac{1}{a} \int_{-a/2}^{a/2} dt = x(0)$$

$$\int_{-\infty}^{+\infty} x(t)\delta(t)dt = x(0)$$

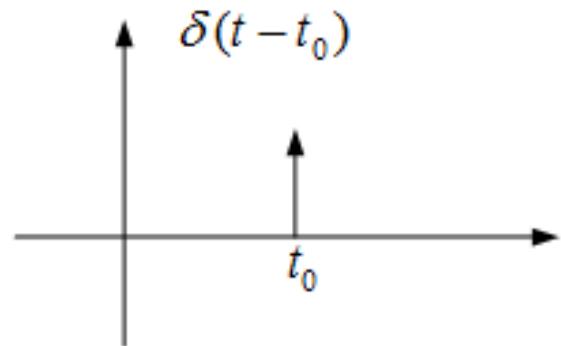
- Ako je  $x(t)$  neprekidna u okolini  $t_0$

$$\int_{-\infty}^{+\infty} x(t+t_0)\delta(t)dt = x(t_0)$$

# Pomereni (šiftovani) Delta impuls

$$\delta(t - t_0) = 0, \text{ za } t \neq t_0$$

$$\int_{-\infty}^{\infty} \delta(t - t_o) dt = \int_{t_o^-}^{t_o^+} \delta(t - t_o) = 1$$



- Ako je  $x(t)$  neprekidna u okolini  $t_0$

$$\int_{-\infty}^{+\infty} x(t) \delta(t - t_0) dt = x(t_0)$$

# Delta impuls, osobine

$$y(t) = Ax(t)\delta(t - t_0) = Ax(t_0)\delta(t - t_0) \quad \text{svojstvo ekvivalencije}$$

$$\delta(-t) = \delta(t)$$

$$\int_{-\infty}^{+\infty} \delta(at) dt = \int_{-\infty}^{+\infty} \delta(-at) dt = \frac{1}{|a|} \int_{-\infty}^{+\infty} \delta(\tau) d\tau \quad \delta(at) = \frac{1}{|a|} \delta(t)$$

$$\delta(a(t - t_0)) = \frac{1}{|a|} \delta(t - t_0)$$

$$\frac{d}{dt} u(t) = \delta(t) \quad u(t) = \int_{-\infty}^t \delta(\tau) d\tau \quad u(0) = \int_{-\infty}^0 \delta(\tau) d\tau = \frac{1}{2} \int_{-\infty}^{\infty} \delta(\tau) d\tau = \frac{1}{2}$$

# Linearni operatori kontinualnih signala, integracija i diferenciranje

$$y(t) = \frac{d}{dt} x(t) = Dx(t)$$

$$S = D^{-1}$$

$$x(t) = SDx(t) = DSx(t)$$

# Linearni operatori kontinualnih signala, integracija

Fundamentalna teorema analize

**Teorema** Neka su  $f(x)$  i  $F(x)$  funkcije realne promenljive na zatvorenom intervalu  $[a, b]$ , tako da važi

$$F'(x) = f(x).$$

Ukoliko je funkcija  $f$  integrabilna na intervalu  $[a, b]$ , onda važi

$$\int_a^b f(x)dx = F(b) - F(a).$$

Za signal ograničen sa leve strane, neodređeni integral je inverzna operacija diferenciranju i nema neodređene konstante

$$\int_{-\infty}^t x(\tau)d\tau = X(t) \quad \frac{d}{dt} X(t) = x(t)$$

# Linearni operatori kontinualnih signala, integracija

$$x(t) = \sin \omega t \cdot u(t), \text{ odrediti } Sx(t)$$

$$\begin{aligned} \int_{-\infty}^t x(\tau) d\tau &= \int_{-\infty}^t \sin \omega \tau \cdot u(\tau) d\tau = \\ &= \left( \int_0^t \sin \omega \tau \cdot d\tau \right) u(t) = \left( -\frac{1}{\omega} \cos \omega t + \frac{1}{\omega} \right) u(t) \end{aligned}$$

# Linearni operatori kontinualnih signala, generalizovano diferenciranje

$$x(t) = g(t)(u(t - t_0) - u(t - t_1)) + g_1(t)u(t - t_1)$$

$$\begin{aligned} x'(t) &= g'(t)(u(t - t_0) - u(t - t_1)) + g_1'(t)u(t - t_1) + \\ &g(t)(\delta(t - t_0) - \delta(t - t_1)) + g_1(t)\delta(t - t_1) = \end{aligned}$$

$$\begin{aligned} &= g'(t)(u(t - t_0) - u(t - t_1)) + g_1'(t)u(t - t_1) + \\ &g(t_0)\delta(t - t_0) - g(t_1)\delta(t - t_1) + g_1(t_1)\delta(t - t_1) = \end{aligned}$$

$$\begin{aligned} &g'(t)(u(t - t_0) - u(t - t_1)) + g_1'(t)u(t - t_1) + \\ &g(t_0)\delta(t - t_0) + (g_1(t_1) - g(t_1))\delta(t - t_1) \end{aligned}$$