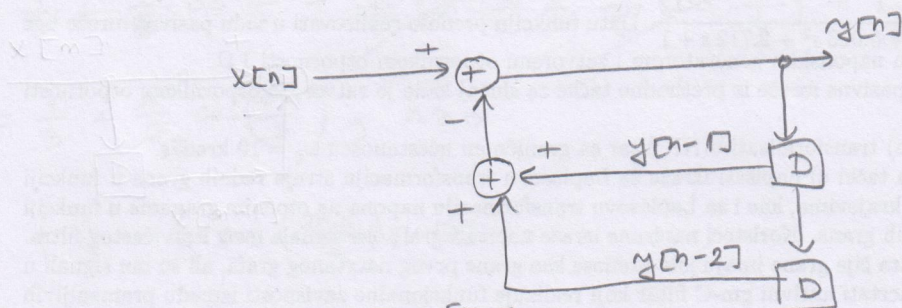


$$① \quad y[n] + y[n-1] + y[n-2] = x[n]$$

$$a) \quad y[n] = -y[n-1] - y[n-2] + x[n]$$



$$b) \quad h_1[n] + h_1[n-1] + h_1[n-2] = \delta[n]$$

$$h_1[0] = 1, \quad h_1[1] = -h_1[0] = -1$$

$$P(\lambda) = \lambda^2 + \lambda + 1$$

$$\lambda_{1,2} = \frac{-1 \pm \sqrt{1-4}}{2} = \frac{-1 \pm j\sqrt{3}}{2} \Rightarrow \text{II квант}$$

$$\rho = 1, \quad \varphi = \frac{2\pi}{3}$$

$$\arctg(\varphi) = -\sqrt{3}$$

$$h[n] = (A \cdot \sin(n\varphi) + B \cos(n\varphi)) \mu[n]$$

$$h[0] = B = 1$$

$$h[1] = A \cdot \underbrace{\sin\left(\frac{2\pi}{3}\right)}_{+\sqrt{3}/2} + B \cdot \underbrace{\cos\left(\frac{2\pi}{3}\right)}_{-1/2} = -1$$

$$A \cdot \frac{\sqrt{3}}{2} = -\frac{1}{2} \Rightarrow A = -\frac{\sqrt{3}}{3}$$

$$h[n] = \left(-\frac{\sqrt{3}}{3} \sin\left(\frac{2\pi}{3}n\right) + \cos\left(\frac{2\pi}{3}n\right) \right) \mu[n]$$

$$h[n] = h_1[n] - h_1[n-1]$$

$$c) \quad y_{p1}[n] = h_1[n] * x[n] = \sum_{m=-\infty}^{+\infty} (A \sin(m\varphi) + B \cos(m\varphi)) \cdot \mu[m] \cdot \mu[n-m] =$$

$$= \mu[n] \cdot \left(-A \cdot \frac{\cos(\varphi(m-\frac{1}{2}))}{2 \sin \frac{\varphi}{2}} + B \cdot \frac{\sin(\varphi(m-\frac{1}{2}))}{2 \sin \frac{\varphi}{2}} \right) \Big|_0^{n+1} =$$

$$= \mu[n] \cdot \left(\frac{\sqrt{3}}{3} \left(\cos\left((n+\frac{1}{2}) \cdot \frac{2\pi}{3}\right) - \cos\left(\frac{\pi}{3}\right) \right) + \sin\left((n+\frac{1}{2}) \cdot \frac{2\pi}{3}\right) + \sin\left(\frac{\pi}{3}\right) \right) =$$

$$= \mu[n] \cdot \left(\frac{1}{3} + \frac{1}{3} \cos\left((n+\frac{1}{2}) \cdot \frac{2\pi}{3}\right) + \frac{1}{\sqrt{3}} \sin\left((n+\frac{1}{2}) \cdot \frac{2\pi}{3}\right) \right)$$

$$y_p[n] = y_{p1}[n] - y_{p1}[n-1]$$

$$y_s[n] = A \sin(n\varphi) + B \cos(n\varphi)$$

$$y_s[0] = B = 1$$

$$y_s[1] = 2 = A \cdot \frac{\sqrt{3}}{2} - \frac{B}{2} \Rightarrow \frac{A\sqrt{3}}{2} = \frac{5}{2}$$

$$A = \frac{5}{\sqrt{3}}$$

$$\cos\left((n+\frac{1}{2})\frac{2\pi}{3}\right) = \cos\frac{n2\pi}{3} \cdot \cos\frac{\pi}{3} - \sin\frac{n2\pi}{3} \cdot \sin\frac{\pi}{3}$$

$$\sin\left((n+\frac{1}{2})\frac{2\pi}{3}\right) = \sin\frac{n2\pi}{3} \cdot \cos\frac{\pi}{3} + \cos\frac{n2\pi}{3} \cdot \sin\frac{\pi}{3}$$

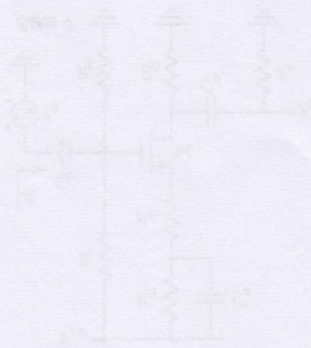
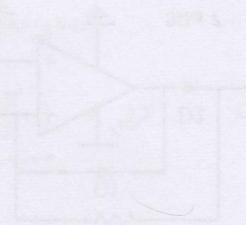
$$y_p[n] = \frac{1}{3} + \frac{1}{6} \cdot \cos\frac{n2\pi}{3} - \frac{\sqrt{3}}{6} \sin\frac{n2\pi}{3} + \frac{\sqrt{3}}{6} \sin\left(\frac{2\pi n}{3}\right) + \frac{\sqrt{3}}{8} \cdot \frac{\sqrt{3}}{2} \cos\left(\frac{2n\pi}{3}\right) =$$

$$= \frac{1}{3} + \frac{4}{6} \cos\left(\frac{2n\pi}{3}\right), \quad n \geq 0$$

$$y_p[n] = \left(\frac{1}{3} + \frac{2}{3} \cos\left(\frac{2n\pi}{3}\right) \right) u[n]$$

$$y_s[n] = \left(\frac{5}{\sqrt{3}} \sin\left(\frac{2n\pi}{3}\right) + \cos\left(\frac{2n\pi}{3}\right) \right) u[n]$$

$$y[n] = \left(\frac{1}{3} + \frac{5}{3} \cos\left(\frac{2n\pi}{3}\right) + \frac{5}{\sqrt{3}} \sin\left(\frac{2n\pi}{3}\right) \right), \quad n \geq 0$$



$$d) (E^2 + E + 1) y_{pr}[n-2] = x[n] - x[n-1]$$

$$y_{pr}[n-2] = \frac{E^{-1} - 1}{E^2 + E + 1} = \frac{1}{P(1)} = \frac{1}{3}$$

$$y_{pr}[n] = \frac{1}{3} u[n]$$

$$y_d[n] = A \sin(n\varphi) + B \cos(n\varphi)$$

из марке c) же: $y[0] = y_s[0] + y_p[0] = 1 + 1 = 2$

$$y_p[0] = \frac{1}{3} + \frac{1}{3} \underbrace{\cos\left(\frac{\pi}{3}\right)}_{1/2} + \frac{1}{\sqrt{3}} \underbrace{\sin\left(\frac{\pi}{3}\right)}_{\sqrt{3}/2} = \frac{1}{3} + \frac{1}{6} + \frac{1}{2} = 1$$

$$y[1] = \underbrace{y_s[1]}_2 + y_p[1] = 2$$

$$y_p[1] = -y_p[0] + x[1] = 0 \quad (\text{на основе формулы})$$

$$y_p[1] = \frac{1}{3} + \frac{1}{3} \cdot \underbrace{\cos\left(\frac{3}{2} \cdot \frac{2\pi}{3}\right)}_{-1} + \frac{1}{\sqrt{3}} \underbrace{\sin\left(\frac{3}{2} \cdot \frac{2\pi}{3}\right)}_0 = 0$$

$$y[n] = y_{pr}[n] + y_d[n] = \frac{1}{3} + A \sin\left(\frac{2\pi n}{3}\right) + B \cos\left(\frac{2\pi n}{3}\right)$$

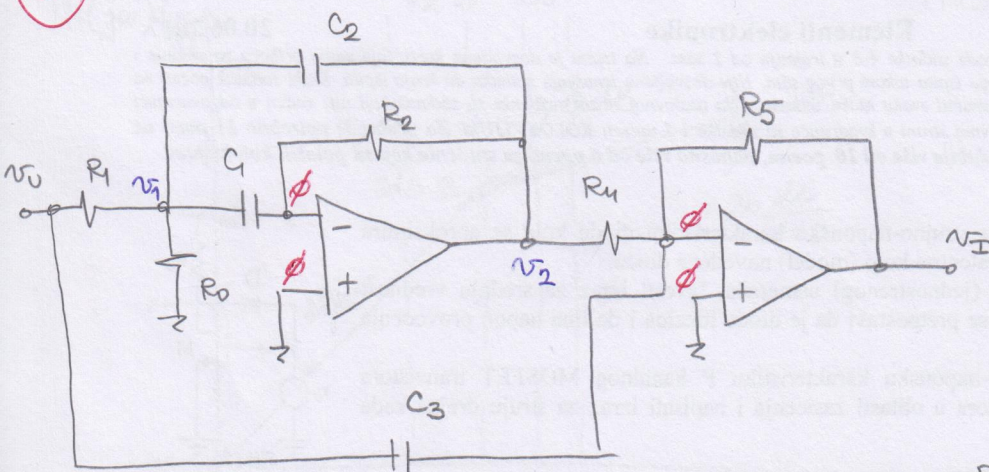
$$y[0] = \frac{1}{3} + B = 2 \Rightarrow B = \frac{5}{3}$$

$$y[1] = \frac{1}{3} + A \cdot \frac{\sqrt{3}}{2} + B \cdot \left(-\frac{1}{2}\right) = \frac{1}{3} - \frac{5}{6} + A \frac{\sqrt{3}}{2} = 2$$

$$A \frac{\sqrt{3}}{2} = 2 + \frac{8}{6} = \frac{5}{2}$$

$$A = \frac{5}{\sqrt{3}}$$

3



$$v_I = -\frac{R_5}{R_4} v_2 - \frac{SC_3 R_5}{R} v_U$$

$$v_2 = -v_I - SC_3 R v_U$$

$$v_2 = -R_2 \cdot SC_1 v_1 = -SC_1 R v_1$$

$$v_1 = \frac{v_I + SC_3 R v_U}{SC_1 R} = \frac{v_I}{SC_1 R} + \frac{v_U}{2}$$

$$\frac{v_1 - v_U}{R_1} + \frac{v_1}{R_0} + SC_1 v_1 + SC_2 (v_1 - v_2) = 0$$

$$\frac{v_U}{R} = \left(\frac{1}{R} + \frac{1}{R_0} + SC \cdot 2 \right) \cdot \frac{v_I + SC_3 R v_U}{SC_1 R} + SC \cdot (v_I + SC_3 R v_U) =$$

$$= v_I \cdot \frac{\frac{1}{R} + \frac{1}{R_0} + 2SC + (SC)^2 R}{SC_1 R} + \frac{SC_3 R \left(\frac{1}{R} + \frac{1}{R_0} + 2SC + (SC)^2 R \right)}{SC_1 R} v_U \quad / \cdot SC_1 R$$

$$v_U \cdot \left(\left(-\frac{1}{R} - \frac{1}{R_0} - 2SC - (SC)^2 R \right) \cdot SC_3 R + SC \right) = v_I \left(\frac{1}{R} + \frac{1}{R_0} + 2SC + (SC)^2 R \right)$$

$$s \left(C - C_3 R \cdot \frac{R + R_0}{R R_0} \right) = s \cdot \left(C - C_3 \frac{R + R_0}{R_0} \right) = 0$$

$$-v_U \cdot \left(2SC \cdot \frac{SC_1 R}{2} + (SC)^2 R \cdot \frac{SC_1 R}{2} \right) = v_I \left(\frac{2}{R} + 2SC + (SC)^2 R \right)$$

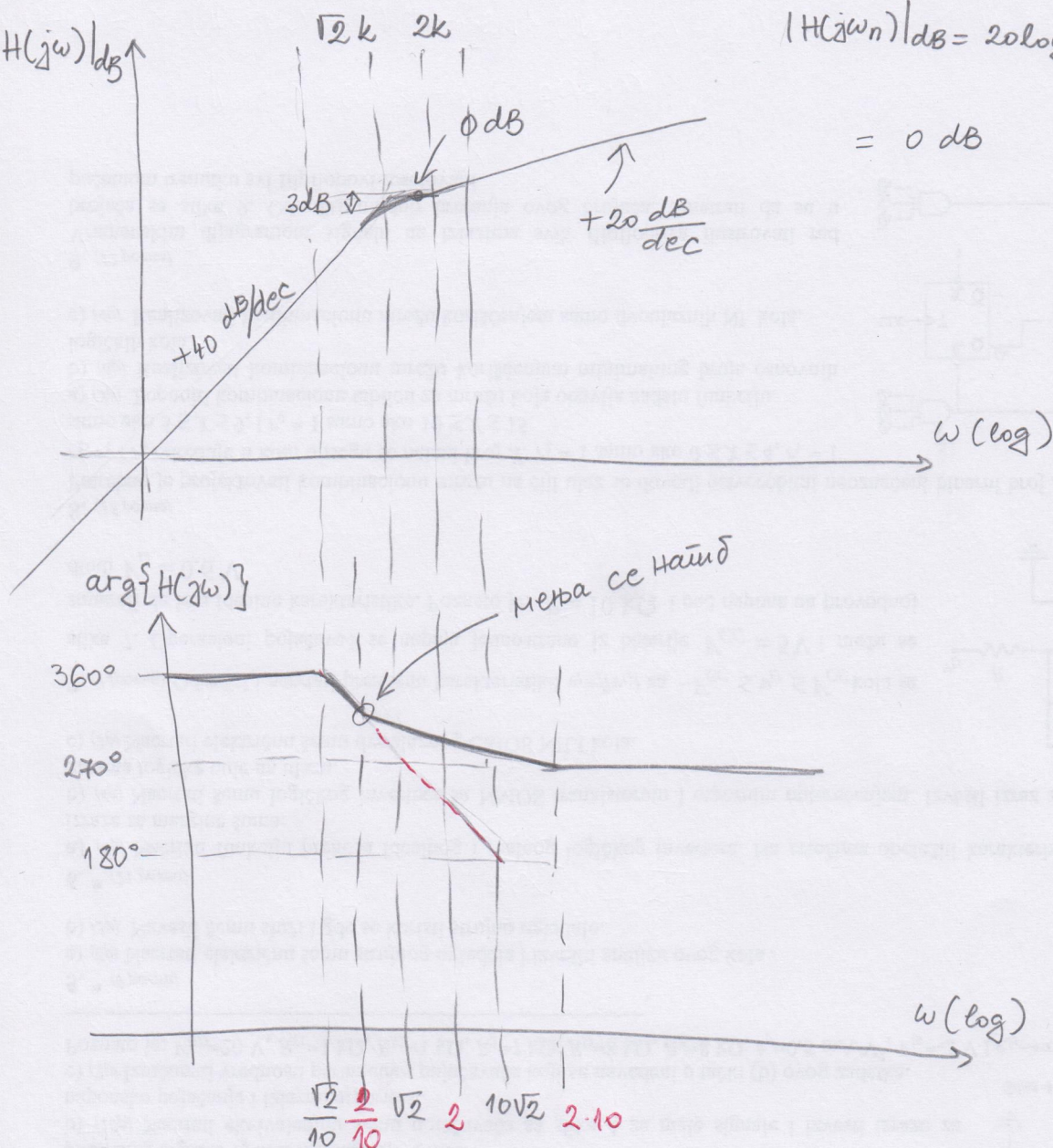
$$H(s) = - \frac{\frac{(SC_1 R)^3}{2} + (SC_1 R)^2}{(SC_1 R)^2 + 2SC_1 R + 2} = - \frac{1}{2} \frac{CR \cdot s^3 + 2s^2}{s^2 + \frac{2s}{CR} + \frac{2}{(CR)^2}} = - \frac{1}{2} \frac{CR s^2 \left(s + \frac{2}{CR} \right)}{s^2 + \frac{2s}{CR} + \frac{2}{(CR)^2}}$$

$$= - \frac{10^{-3}}{2} \frac{s^2 (s + 2000)}{(s^2 + 2000s + 2 \cdot 10^6)}$$

b)

$$|H(j\omega)|_{dB}$$

$$|H(j\omega_n)|_{dB} = 20 \log_{10} \left| -5 \cdot 10^4 \frac{\omega_n^2 \cdot \omega_n}{\omega_n^2} \right| = 0 \text{ dB}$$

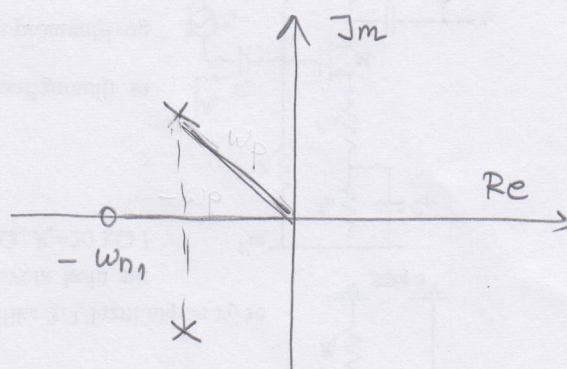


$$H(s) = -\frac{10^{-3}}{2} \cdot \frac{(s + \omega_{n1}) \cdot s^2}{(s^2 + \frac{s\omega_p}{Q} + \omega_p^2)}$$

$$\omega_{n1} = 2000 \frac{\text{rad}}{\text{s}}$$

$$\omega_p = \sqrt{2} \cdot 10^3 \frac{\text{rad}}{\text{s}}$$

$$Q = \frac{\sqrt{2}}{2}$$



c) Кога може да ради као пропусник високих уфестаносити.

3. Kontinualni LTI system je opisan diferencijalnom jednačinom: $(D^2 - 1)y(t) = (D + 2)x(t)$. Rešavanjem u vremenskom domenu

a) [10] odrediti impulsni odziv sistema.

b) [20] Odrediti sopstveni odziv sistema ako je $x(t) = (\cos 3t + \sin 3t)u(t)$

Resenje:

Kada je red polinoma P veci od reda polinoma Q tada ne mogu da se dobiju impulsi u prinudnom odzivu ($y(t)$ ne sadrzi $\delta(t)$ i njegove izvode)

Primenom $Q(D)$ na $x(t)$ dobija se $f(t) = f_1(t) + f_2(t)$ pri cemu $f_1(t)$ ne sadrzi impulse a $f_2(t)$ sadrzi samo impulse.

Sopstveni odziv moze da se dobije superpozicijom na odvojeno $f_1(t)$ i $f_2(t)$. Odziv na $f_1(t)$ se moze dobiti operacionim racunom jer $f_1(t)$ ne sadrzi impulse (preinicijalni uslovi = postinicijalni uslovi = 0) dok je odziv na $f_2(t)$ vec odredjen u tacki a)

2) a) $P(D)y(t) = Q(D)x(t)$ $\boxed{\text{RED}(P) > \text{RED}(Q) \Rightarrow \text{NEMA } \delta \text{ i } \delta'$

$$s_1(t) = c_1 e^{-t} + c_2 e^t + \frac{1}{P(D)} = c_1 e^{-t} + c_2 e^t - 1; t > 0$$

$$s_1'(t) = -c_1 e^{-t} + c_2 e^t; t > 0$$

$$s_1(0^+) = s_1(0^-) = 0$$

$$\begin{cases} c_1 + c_2 - 1 = 0 \\ -c_1 + c_2 = 0 \end{cases} \Rightarrow \begin{cases} c_1 + c_2 = 1 \\ c_1 - c_2 = 0 \end{cases} \Rightarrow c_1 = c_2 = \frac{1}{2} \Rightarrow \boxed{s_1(t) = \frac{1}{2}(e^t + e^{-t}) - 1}$$

$$\boxed{h_1(t) = s_1'(t) = \left(-\frac{1}{2}e^{-t} + \frac{1}{2}e^t\right)u(t)}$$

$$h(t) = (D+2)h_1(t) = \left(\frac{1}{2}e^t + \frac{1}{2}e^t - e^t\right)u(t) = \left(-\frac{1}{2}e^{-t} + \frac{3}{2}e^t\right)u(t)$$

ау одређеном случају $x(t)$

b) $f(t) = (D+2)x(t)$ $\left(\begin{smallmatrix} \text{Д.Е. НА СТРАНИ ЈЕДНАЧ. УМЕ} \\ \text{САДРЖИ } \delta \text{ И } \delta' \dots \end{smallmatrix}\right)$

$$f(t) = (-3\sin 3t + 2\cos 3t)u(t) +$$

$$+ (\cos 3t + \sin 3t)\delta(t) + 2(\cos 3t + \sin 3t)u(t)$$

$$f(t) = \underbrace{(5\cos 3t - \sin 3t)u(t)}_{f_1(t)} + \underbrace{\delta(t)}_{f_2(t)} = f_1(t) + f_2(t)$$

$P(D)y(t) = f_1(t) + f_2(t)$ $y(t) = y_1(t) + y_2(t)$
 $P(D)y_1(t) = f_1(t)$ НЕНА } СУ ПЕРПОЗИЦИЈА
 $P(D)y_2(t) = f_2(t)$ НАА } С А ДИСТЕН

$$\boxed{y_2(t) = h_1(t)}$$

$$y_1(t) = c_1 e^{-t} + c_2 e^t + \frac{1}{P(D)} (5\cos 3t - \sin 3t); t > 0$$

$$y_1(t) = c_1 e^{-t} + c_2 e^t + \frac{1}{-9-1} (5\cos 3t - \sin 3t)$$

$$y_1'(t) = -c_1 e^{-t} + c_2 e^t - \frac{1}{10} (-15\sin 3t - 3\cos 3t)$$

$$y_1(0^+) = 0 \quad c_1 + c_2 - \frac{1}{10} \cdot 5 = 0$$

$$y_1'(0^+) = 0 \quad -c_1 + c_2 + \frac{1}{10} \cdot 3 = 0$$

$$\boxed{c_1 = +\frac{4}{10} \quad c_2 = +\frac{1}{10}}$$

$$y(t) = -\frac{1}{2}e^{-t} + \frac{1}{2}e^t + \frac{4}{10}e^{-t} + \frac{1}{10}e^{+t} - \frac{1}{10}(5\cos 3t - \sin 3t) \quad t > 0$$

$$y(t) = -\frac{1}{10}e^{-t} + \frac{6}{10}e^t - \frac{1}{10}(5\cos 3t - \sin 3t) \quad t > 0$$

Drugi nacin:

Ako je odziv na $x(t)$ jednak $y_1(t)$, tada je odziv na $Q(D)x(t)$ jednak $Q(D)y_1(t)$

$x(t)$ ne sadrzi impulse pa moze da se resi operacionim racunom

$$y_1(t) = c_1 e^{-t} + c_2 e^t - \frac{1}{10}(\cos 3t + \sin 3t) \quad t > 0$$

$$\rightarrow y_1'(t) = -c_1 e^{-t} + c_2 e^t - \frac{1}{10}(-3\sin 3t + 3\cos 3t)$$

$$\begin{cases} y_1(0) = 0 \Rightarrow c_1 + c_2 - \frac{1}{10} = 0 & c_1 = -\frac{1}{10} \\ y_1'(0) = 0 \Rightarrow -c_1 + c_2 - \frac{1}{10} \cdot 3 = 0 & c_2 = \frac{2}{10} \end{cases}$$

$$y_1(t) = -\frac{1}{10}e^{-t} + \frac{2}{10}e^t - \frac{1}{10}(\cos 3t + \sin 3t)$$

$$y_1'(t) = \frac{1}{10}e^{-t} + \frac{2}{10}e^t - \frac{3}{10}(\cos 3t - \sin 3t)$$

$$y(t) = y_1'(t) + 2y_1(t) =$$

$$= \frac{1}{10}e^{-t} - \frac{2}{10}e^{-t} + \frac{2}{10}e^t + \frac{4}{10}e^t - \frac{1}{10}(5\cos 3t + \sin 3t)$$

$$= -\frac{1}{10}e^{-t} + \frac{6}{10}e^t - \frac{1}{10}(5\cos 3t - \sin 3t) ; t > 0$$

Komenta za konvoluciju

Direktna primena konvolucije i parcijalna integracija, su u ovakvom slucaju mukotrpan posao podlozan greskama pa ga ne treba koristiti

Po nekad je moguće rešiti konvolucionni integral bez parcijalne integracije: U ovom slucaju ako se nadje odziv na kompleksnu eksponencijalnu pobudu e^{j3t} , pa se u resenju odvoje imaginarni i realni deo, dobice se odzivi na sinus i kosinus

$$g(t) = x_1(t) + jx_2(t)$$

$$g(t) = e^{j3t}$$

$$g(t) \neq h(t) \Rightarrow$$

Одзнача на $g \in \mathbb{C}$ је $\in \mathbb{Z}$

Одзнача на $x(t) = x_1(t) + jx_2(t)$

$j \in \mathbb{Z}$ је због реалног и имаг. дела

Одзнача на $g(t)$!

$$e^t \times e^{j3t} = e^{at} \times e^{bt} = \frac{e^t - e^{j3t}}{1-3j}$$

$$e^{-t} \times e^{j3t} = e^{-at} \times e^{bt} = \frac{e^{-t} - e^{j3t}}{1-3j}$$

$$\frac{1}{2} \left(\frac{e^{-t} - e^{j3t}}{1-3j} \right) + \frac{3}{2} \left(\frac{e^t - e^{j3t}}{1-3j} \right)^{1+3j} =$$

$$= \frac{1}{2} \cdot \frac{1}{10} \left((e^{-t} - \cos 3t - j \sin 3t)(1-3j) + 3(e^t - \cos 3t - j \sin 3t)(1+3j) \right) =$$

$$= \frac{1}{2} \cdot \frac{1}{10} \left((e^{-t} - \cos 3t - j \sin 3t - 3j e^{-t} + 3j \cos 3t - 3 \sin 3t) + \right.$$

$$\left. + 3(e^t - \cos 3t - j \sin 3t + 3j e^t - 3j \cos 3t + 3 \sin 3t) \right)$$

Раздвајају се имагинарни и реални део
а затим се саберу

$$y(t) = -\frac{1}{10} e^{-t} + \frac{6}{10} e^t - \frac{1}{10} (5 \cos 3t + \sin 3t)$$

4.

a) [5] Odrediti Furijeovu transformaciju signala $x_F(t) = \sin(\pi t / 2)(u(t) - u(t-1))$

b) [5] Odrediti koeficijente razvoja u kompleksni Furijeov red signala kome je osnovna perioda trajanja 2 i koji je na prvoj osnovnoj periodi jednak signalu iz tačke a)

$$4) a) u(t) - u(t-1) = \text{rect}\left(t - \frac{1}{2}\right)$$

$$\mathcal{F}\{\text{rect}(t - \frac{1}{2})\} = \text{sinc} \frac{\omega}{2\pi} e^{-j\frac{\omega}{2}}$$

$$X_F(j\omega) = \frac{1}{2\pi} \text{sinc} \frac{\omega}{2\pi} e^{-j\frac{\omega}{2}} * j\pi (S(\omega + \omega_0) - S(\omega - \omega_0)) \quad \omega_0 = \frac{\pi}{2}$$

$$X_F(j\omega) = \frac{j}{2} \left(\text{sinc} \frac{\omega + \omega_0}{2\pi} e^{-j\frac{\omega + \omega_0}{2}} - \text{sinc} \frac{\omega - \omega_0}{2\pi} e^{-j\frac{\omega - \omega_0}{2}} \right)$$

$$b) X[k] = \frac{1}{T_F} X_F(j\omega) \Big|_{\omega = k\omega_F} \quad T_F = 2$$

$$\omega_F = \frac{2\pi}{T_F} = \pi$$

$$X[k] = \frac{j}{4} \left(\text{sinc} \frac{k\pi + \frac{\pi}{2}}{2\pi} e^{-j\frac{k\pi + \frac{\pi}{2}}{2}} - \text{sinc} \frac{k\pi - \frac{\pi}{2}}{2\pi} e^{-j\frac{k\pi - \frac{\pi}{2}}{2}} \right)$$